

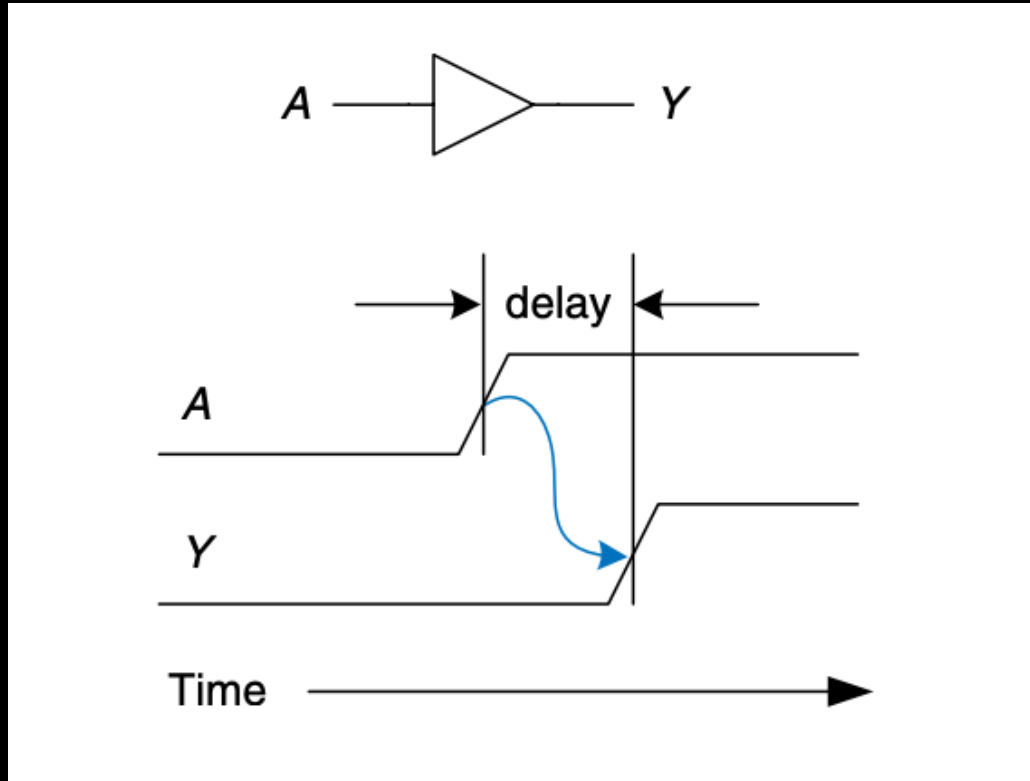
CSC258 Week 6

Circuit Timing

Timing

- So far we have been worrying whether a circuit is correct.
- Now let's think about how to make a circuit fast.
- Key concept: latency
 - propagation delay
 - contamination delay

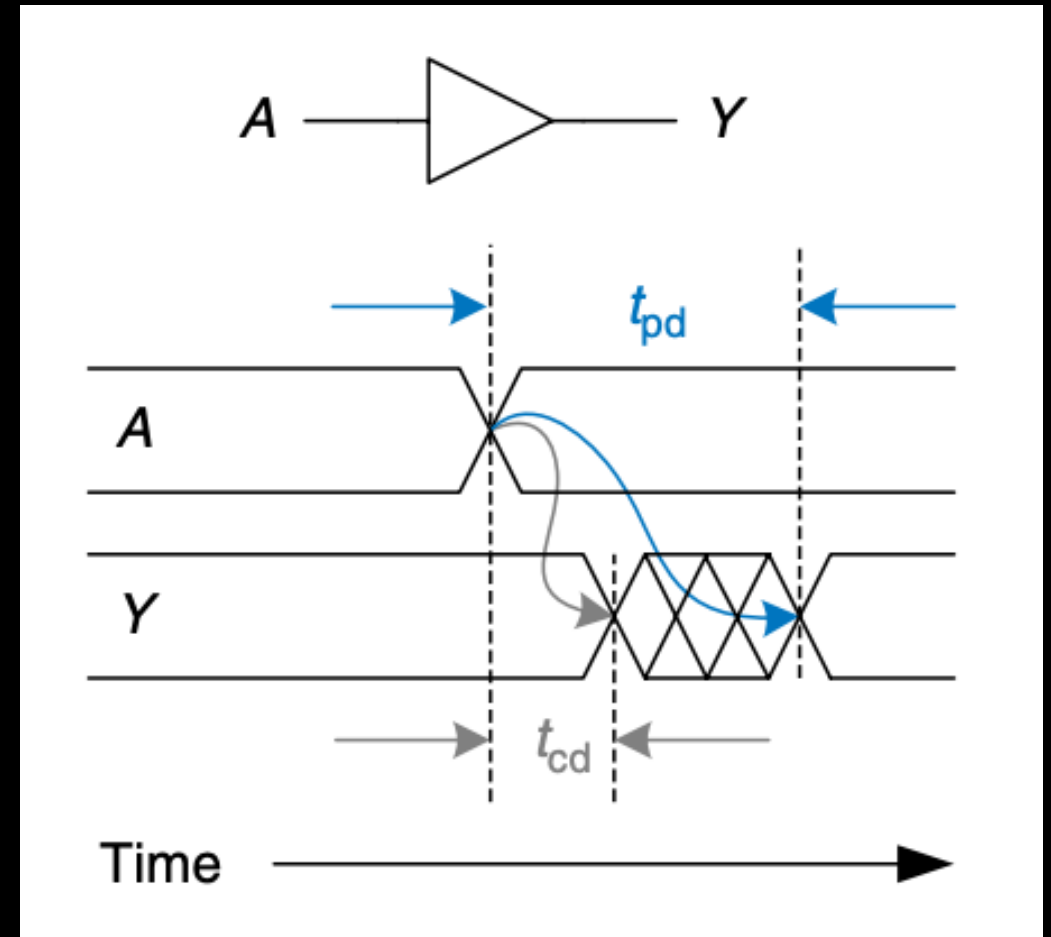
Delay Example



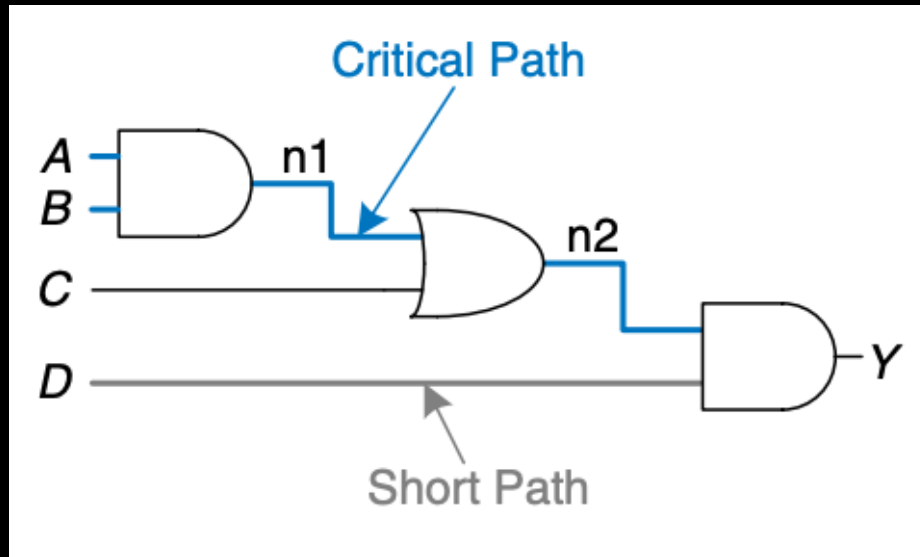
- We measure the interval between the two “50% points” of the changing signals

Propagation & Contamination Delay

- **Propagation delay:** the maximum time from when an input changes until the output or outputs reach their final value.
- **Contamination delay:** the minimum time from when an input changes until any output starts to change its value.

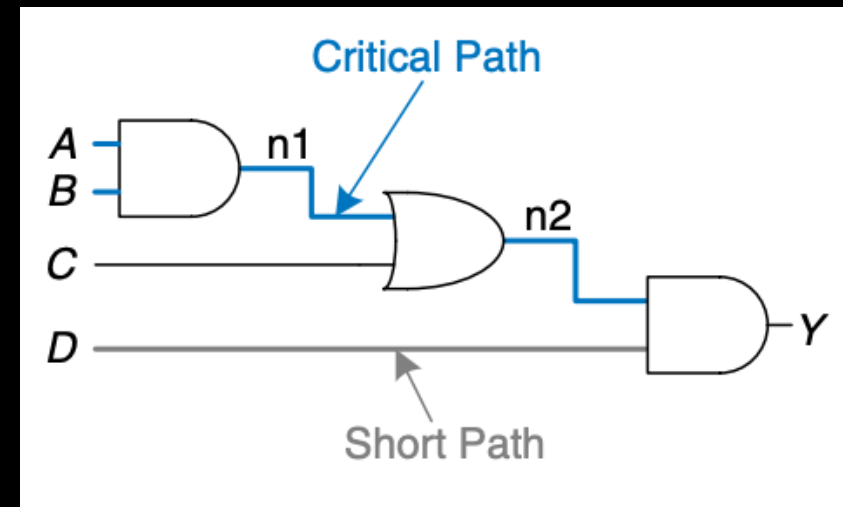


Given a circuit diagram,
calculate its propagation delay
and contamination delay



Need to know

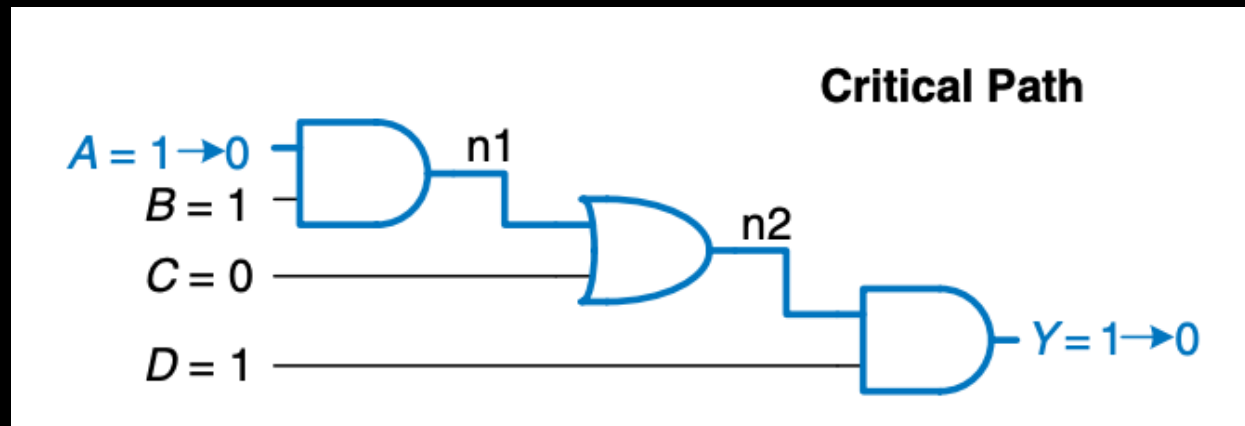
- The propagation and contamination delay of each logic gate used



Gate	t _{pd} (propagation)	t _{cd} (contamination)
2-input AND	100 picoseconds	60 picoseconds
2-input OR	120 picoseconds	40 picoseconds

Calculate Propagation Delay

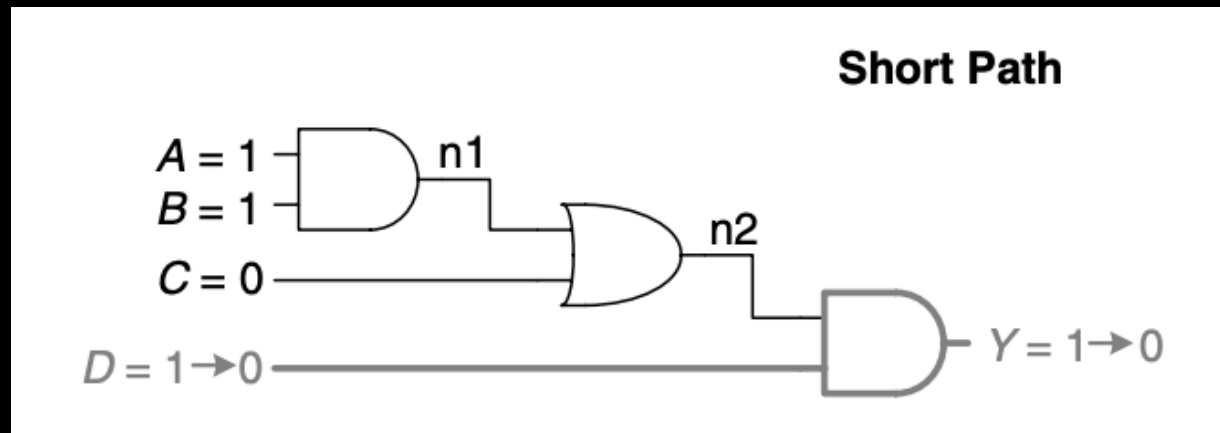
- Find the **critical path** (path with the largest number of gates)
- then sum up the **propagation** delay of all the gates on the critical path
- $100 + 120 + 100 = 320$ picoseconds



Gate	t _{pd}	t _{cd}
2-input AND	100 ps	60 ps
2-input OR	120 ps	40 ps

Calculate Contamination Delay

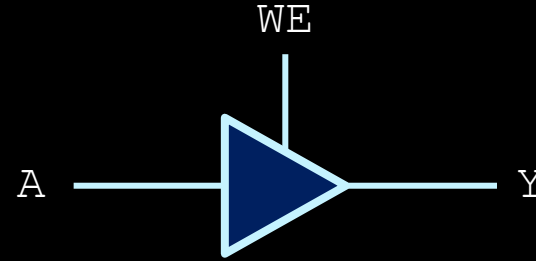
- Find the **short path** (path with the smallest number of gates)
- then sum up the **contamination** delay of all the gates on the short path
- 60 seconds



Gate	t _{pd}	t _{cd}
2-input AND	100 ps	60 ps
2-input OR	120 ps	40 ps

Knowing how to calculate delays allows us to design circuits that are fast.

Quick intro: Tri-state buffer

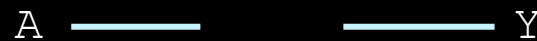


WE	A	Y
0	x	z
1	0	0
1	1	1

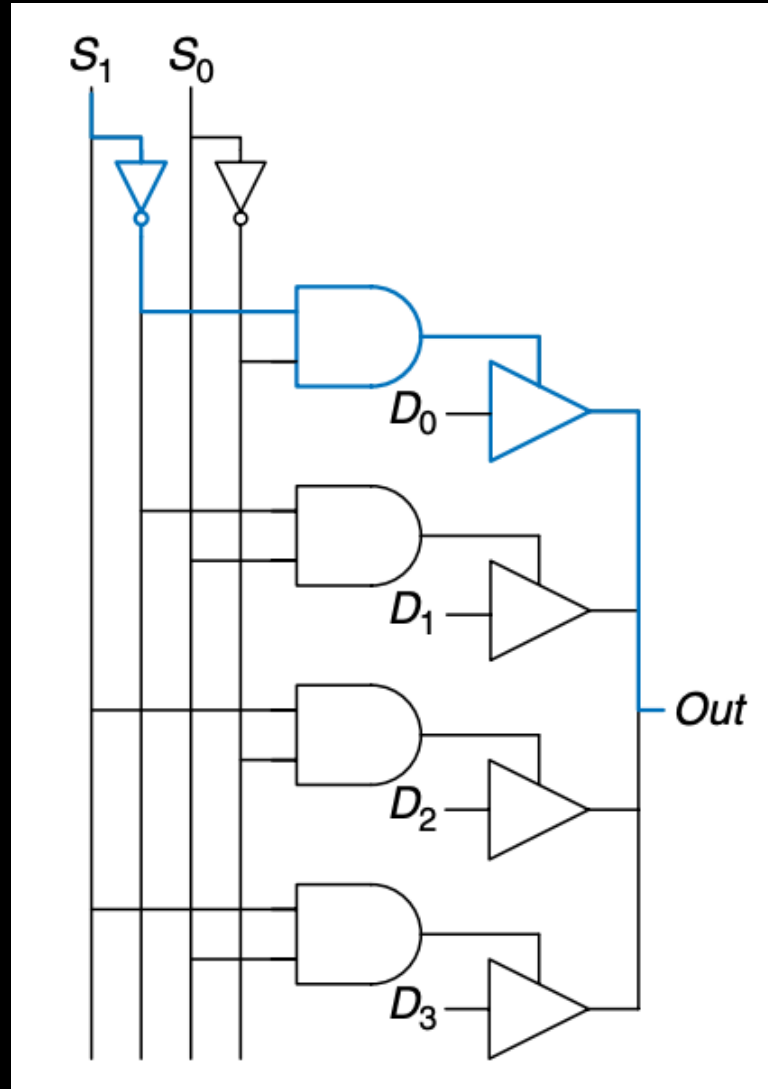
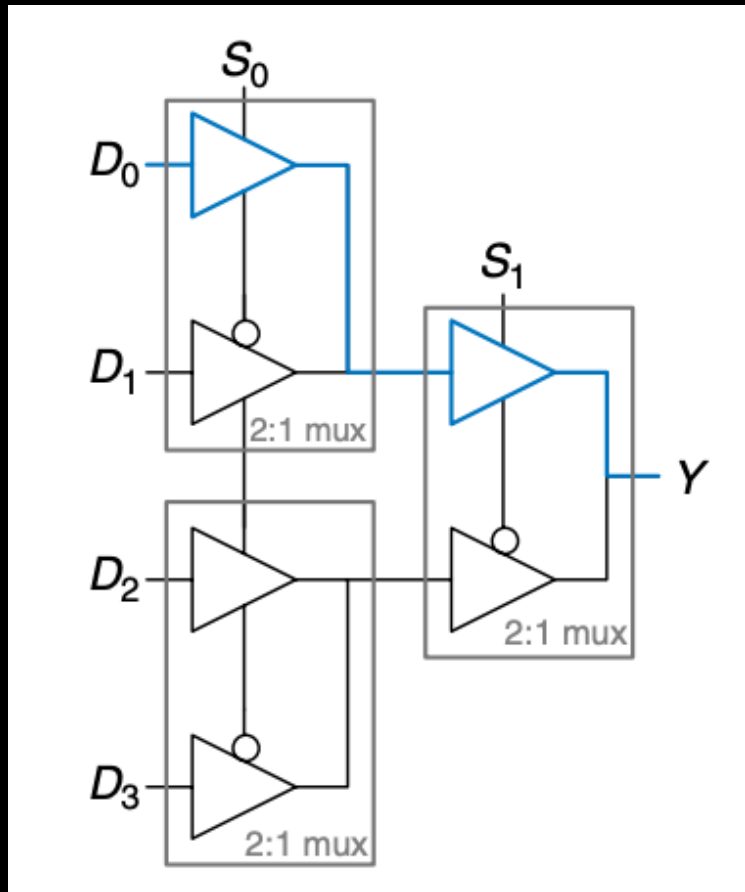
WE = 1



WE = 0

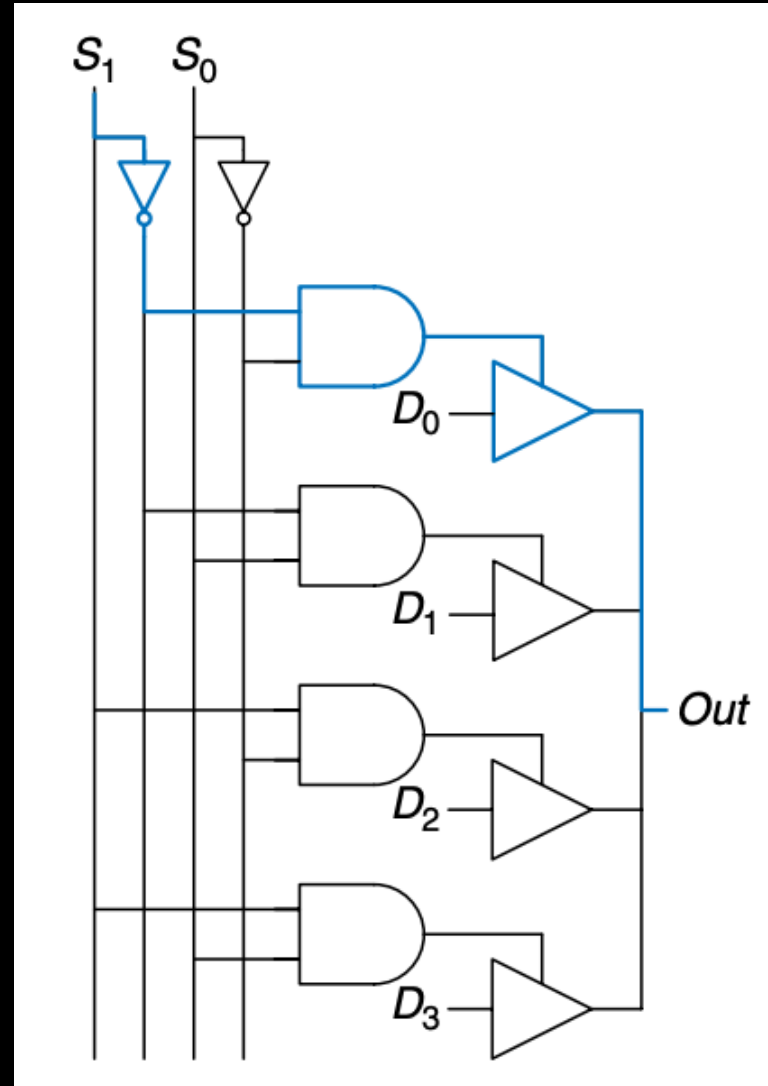
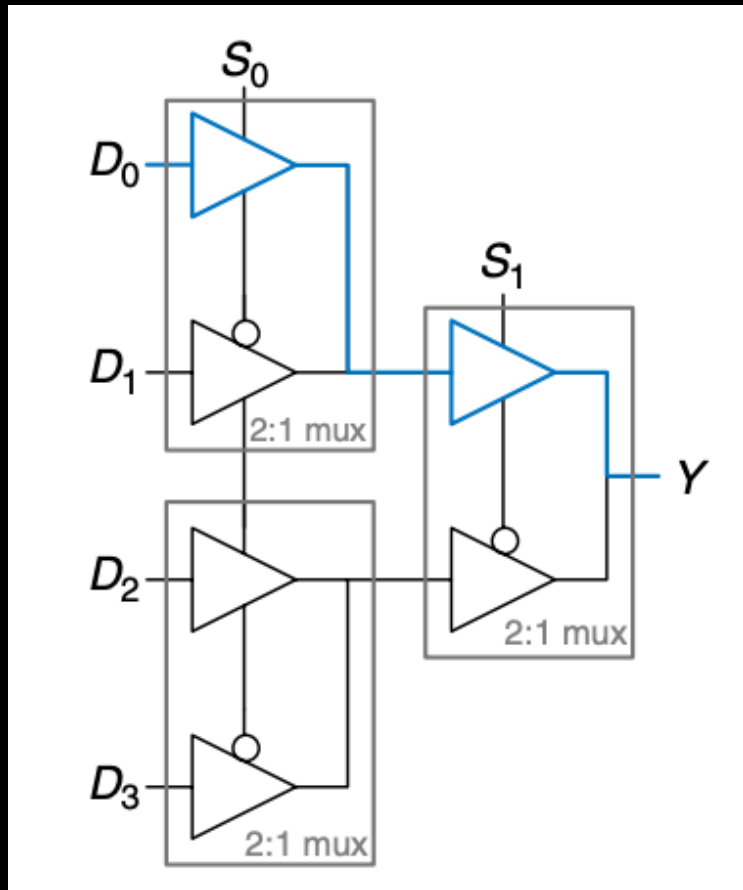


Example: design fast circuit

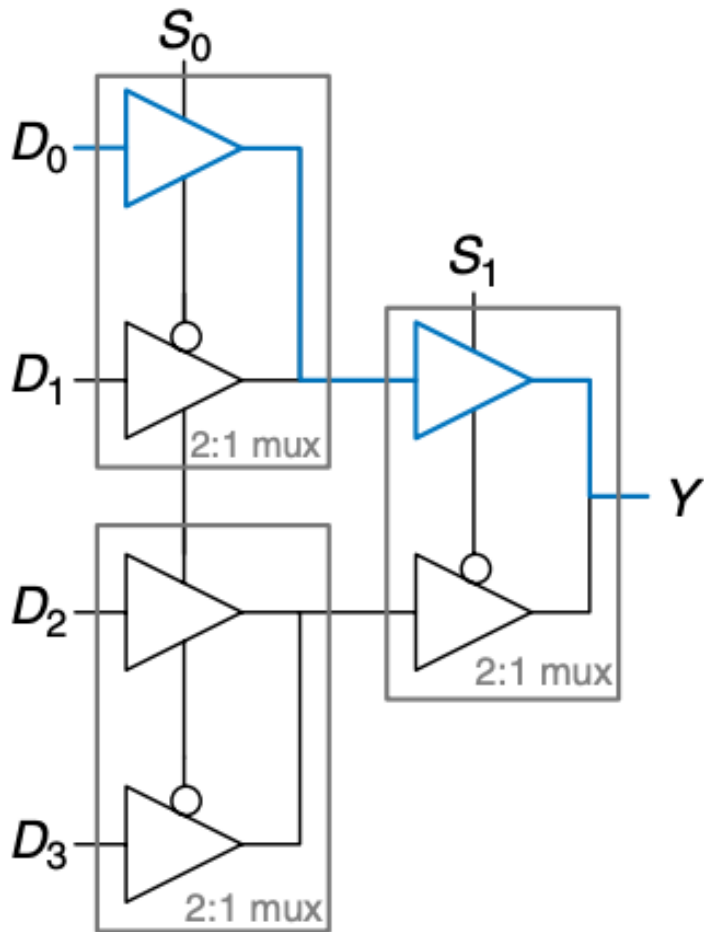


4-1 muxes

Example: design fast circuit

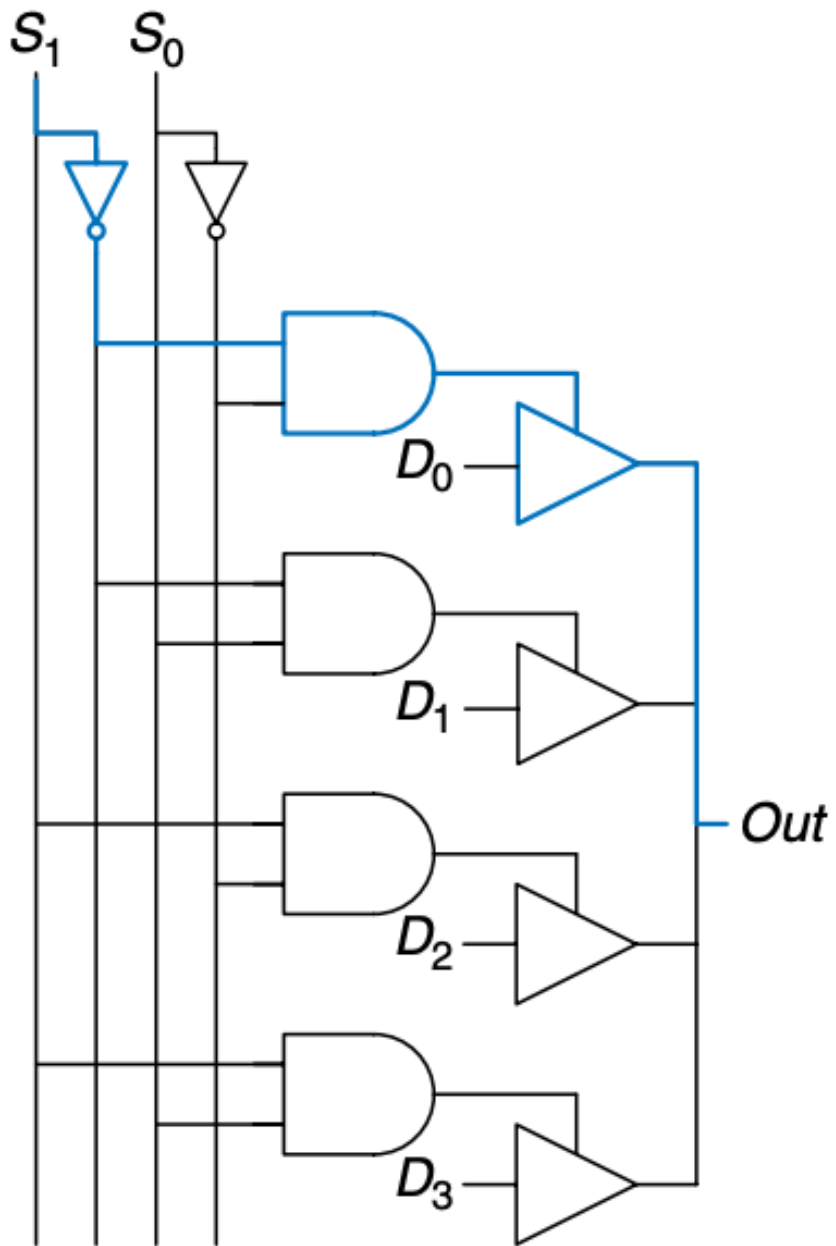


- We care about the **propagation** delays of the two circuits.
 - it tells us “how soon I can get the answer”
- More specifically, we care about the D-to-Y delay and S-to-Y delay because D and S may arrive at different time.



Gate	t_{pd} (ps)
NOT	30
2-input AND	60
3-input AND	80
4-input OR	90
tristate (A to Y)	50
tristate (enable to Y)	35

- D-to-Y propagation delay:
- $2 \times \text{TRISTATE_AY} = 100$
- S-to-Y propagation delay
- $\text{TRISTATE_ENY} + \text{TRISTATE_AY}$
- $= 35 + 50 = 85$

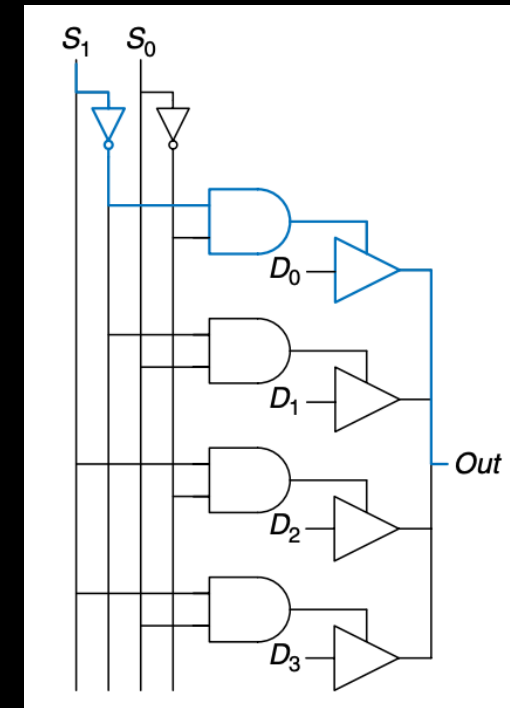
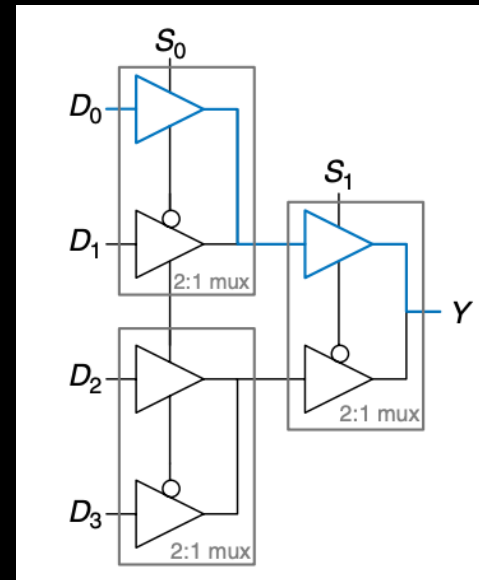


Gate	t_{pd} (ps)
NOT	30
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4-input OR	90
tristate (A to Y)	50
tristate (enable to Y)	35

- D-to-Y propagation delay:
- $TRISTATE_AY = 50$
- S-to-Y propagation delay
- $NOT + AND2 + TRISTATE_ENY$
- $= 30 + 60 + 35 = 125$

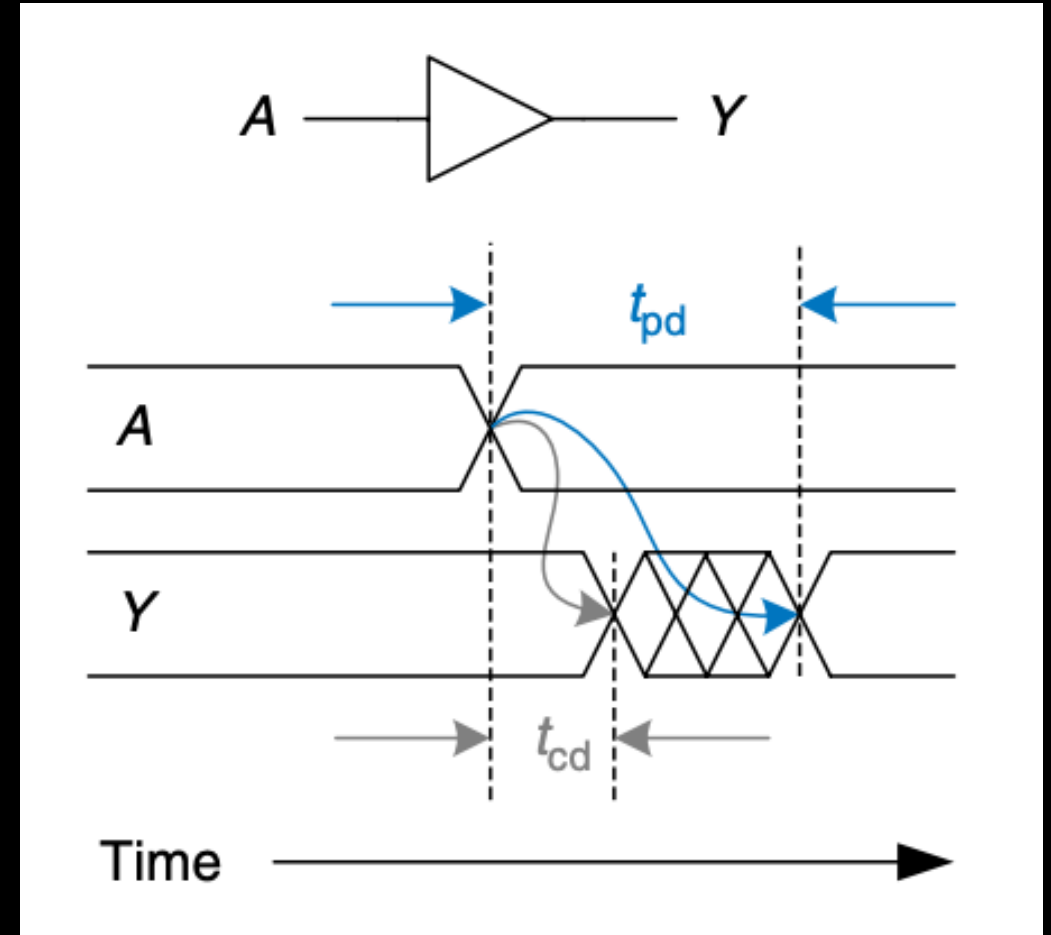
Analysis result

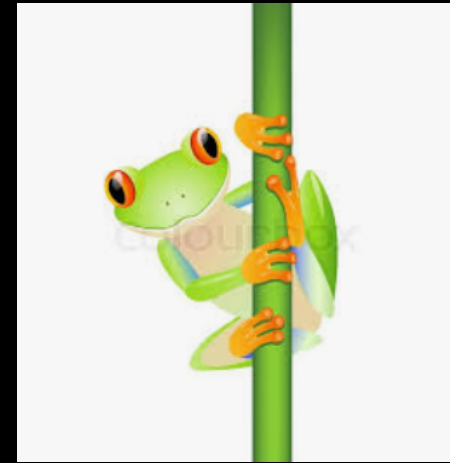
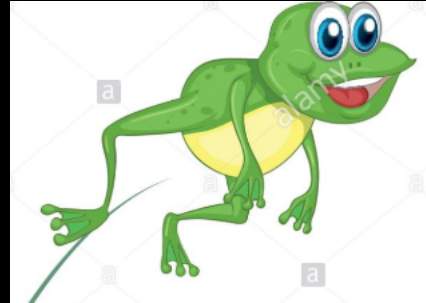
- Circuit 1 propagation:
 - D-to-Y: 100 ps
 - S-to-Y: 85 ps
- Circuit 2 propagation
 - D-to-Y: 50 ps
 - S-to-Y: 125 ps
- Which circuit is faster?
 - What if D and S arrive at the same time?
 - What if D arrives earlier than S?
 - What if S arrives earlier than D?



Delays: the lower/higher, the better?

- Propagation delay, typically, should be upper-bounded.
 - shorter propagation means getting answer faster
 - How to make it lower?
 - shorten the critical path
- Contamination delay, typically, should be lower-bounded
 - want to reliably sample the value before change.
 - How to make it longer?
 - add **buffers** to the short path





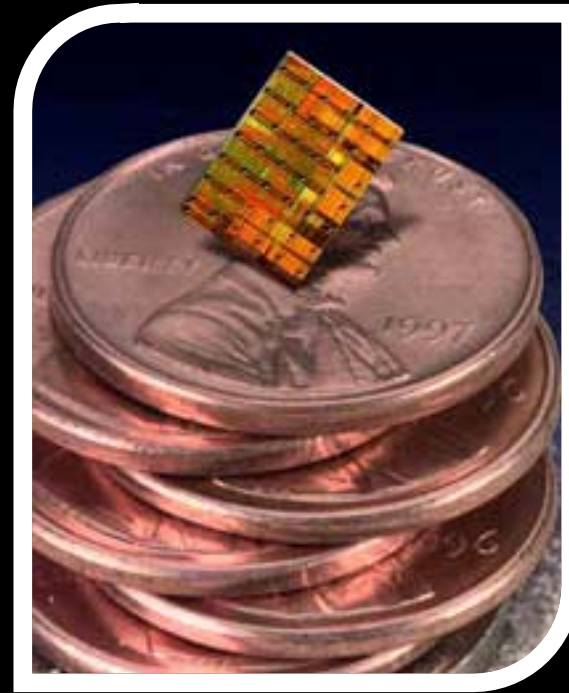
New Topic:
**Processor
Components**



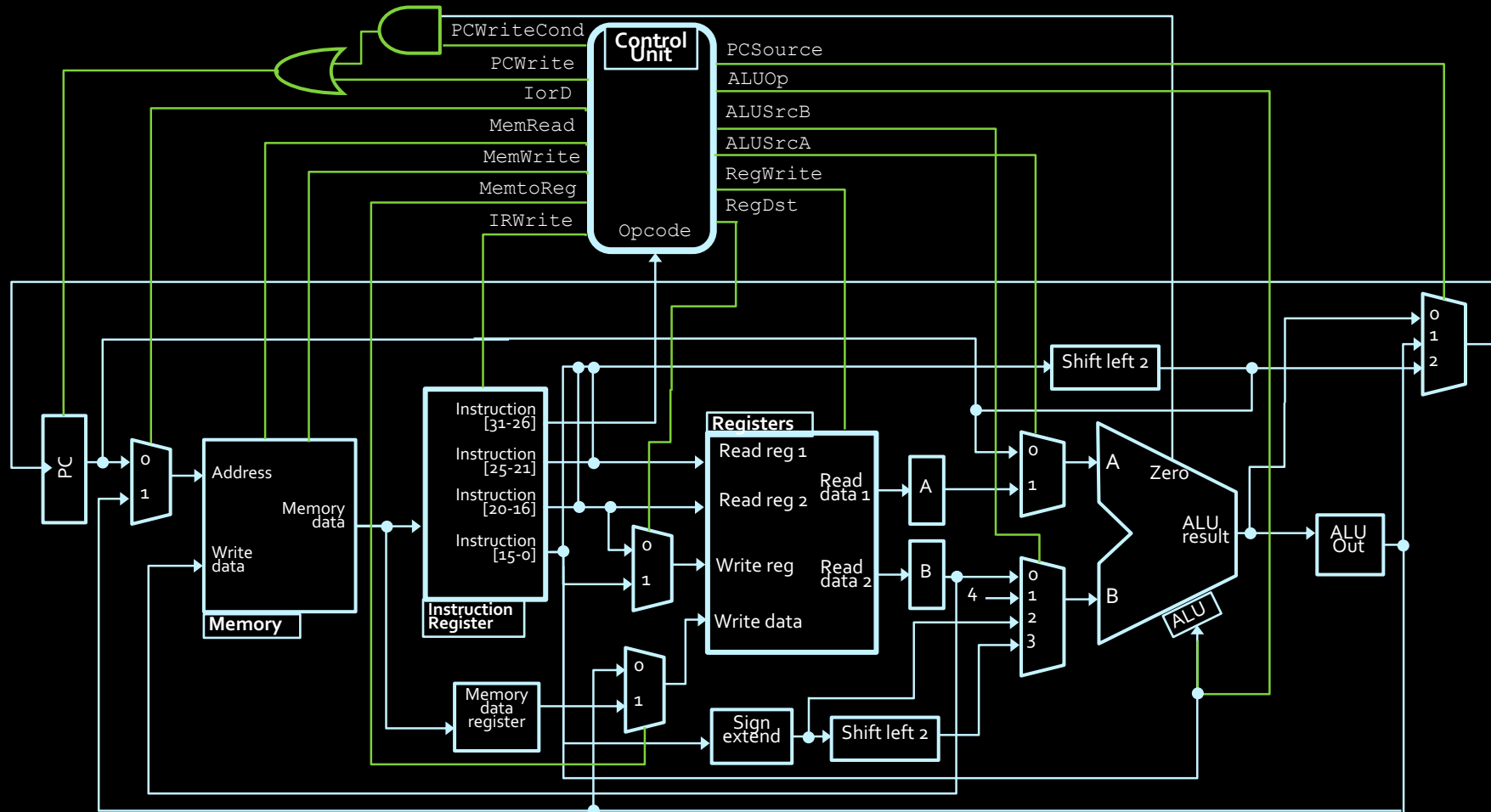
Using what we have learned so far
(combinational logic, devices, sequential
circuits, FSMs), **how do we build a processor?**

Microprocessors

- So far, we've been talking about making devices, such as adders, counters and registers.
- The ultimate goal is to make a **microprocessor**, which is a digital device that processes input, can store values and produces output, according to a set of on-board instructions.

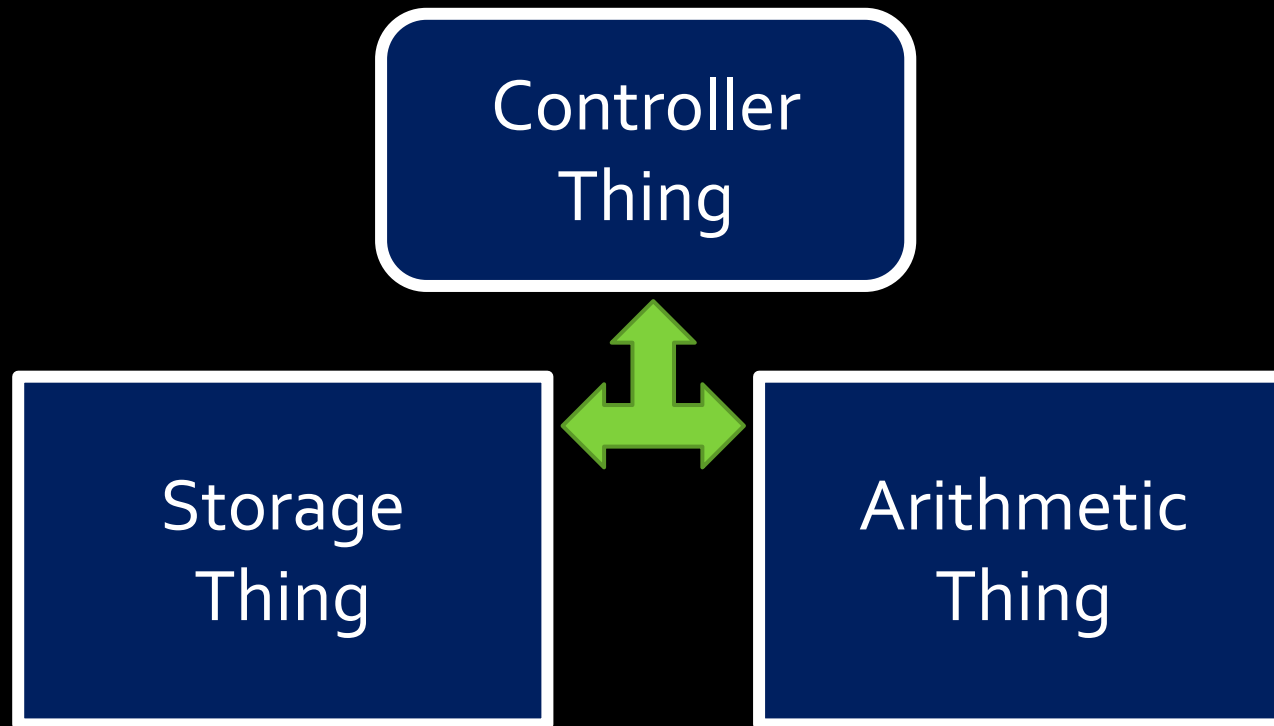


The Final Destination



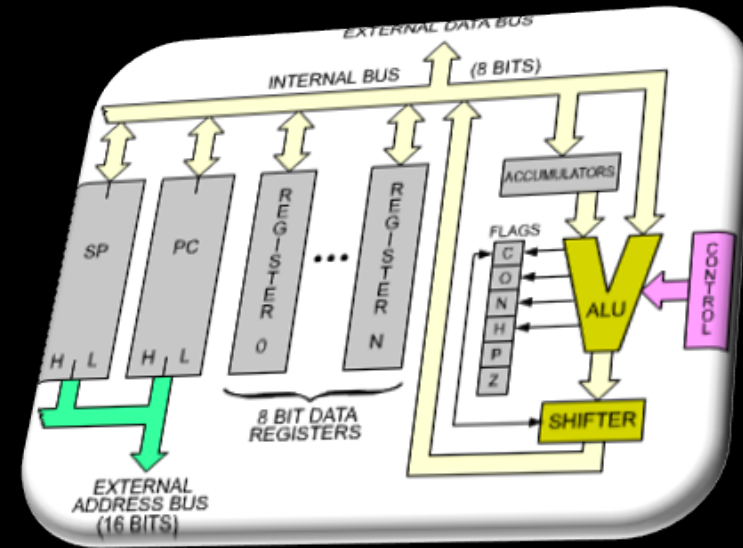
Deconstructing processors

- Processors aren't so bad when you consider them piece by piece:



Microprocessors

- These devices are a combination of the units that we've discussed so far:
 - **Registers** to store values.
 - **Adders** and **shifters** to process data.
 - **Finite state machines** to control the process.
- Microprocessors are the basis of all computing since the 1970's, and can be found in nearly every sort of electronics.

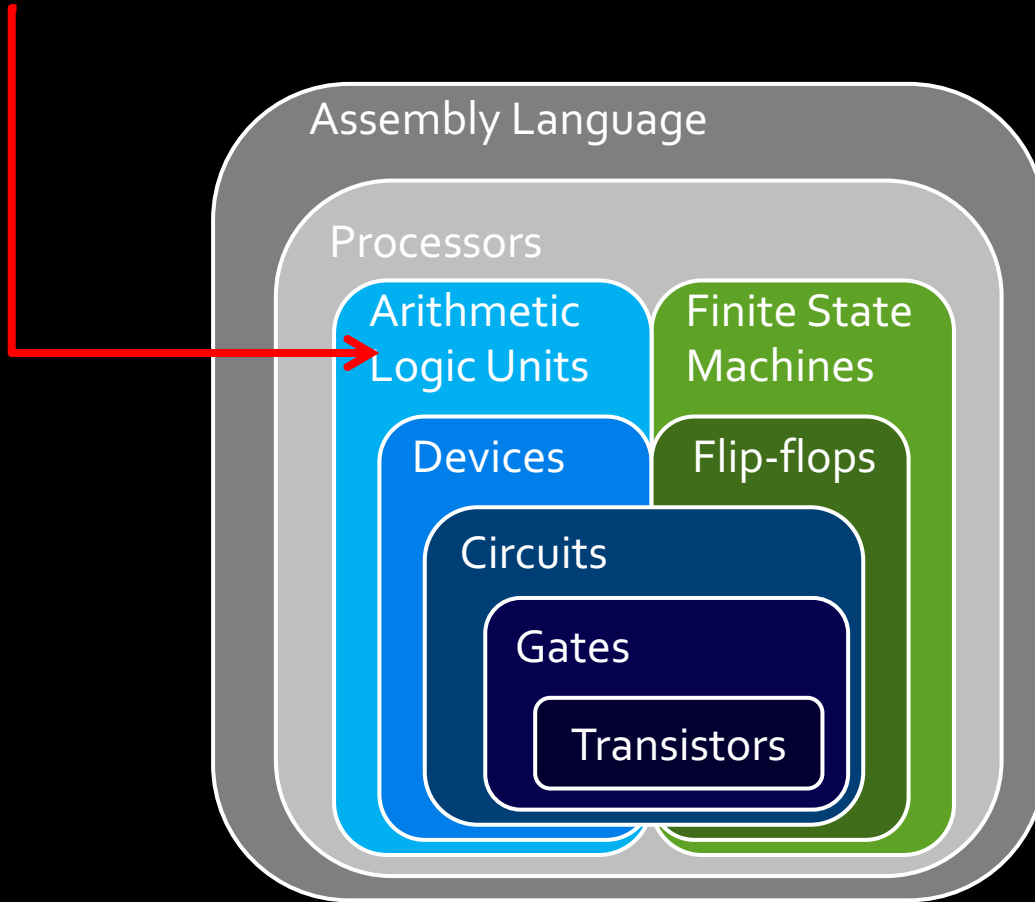


The “Arithmetic Thing”

aka: the Arithmetic Logic Unit (ALU)

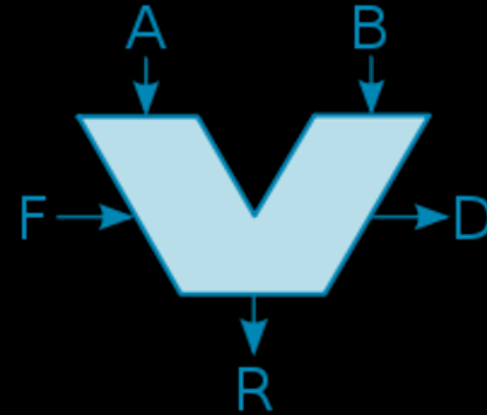


We are here



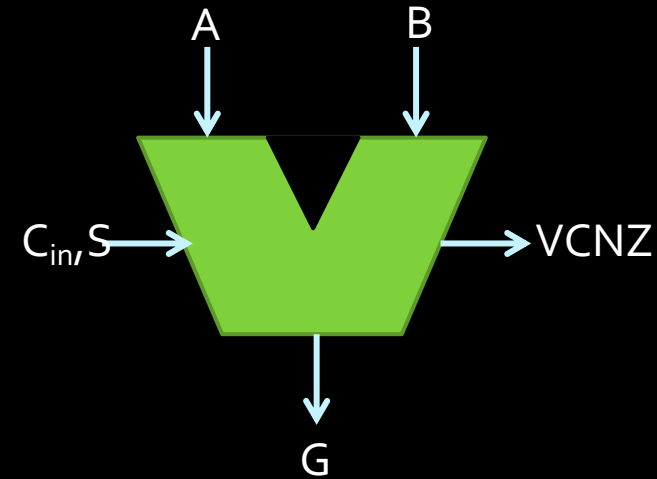
Arithmetic Logic Unit

- The first microprocessor applications were calculators.
 - Recall the unit on adders and subtractors.
 - These are part of a larger structure called the **arithmetic logic unit** (ALU).
- This larger structure is responsible for the processing of all data values in a basic CPU.



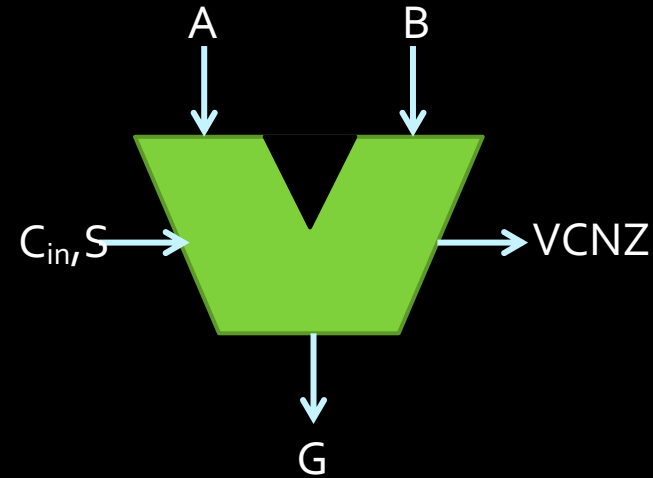
ALU inputs

- The ALU performs all of the arithmetic operations covered in this course so far, and logical operations as well (AND, OR, NOT, etc.)
 - A and B are the operands
 - The select bits (S) indicate which operation is being performed (S₂ is a mode select bit, indicating whether the ALU is in arithmetic or logic mode).
 - The carry bit C_{in} is used in operations such as incrementing an input value or the overall result.



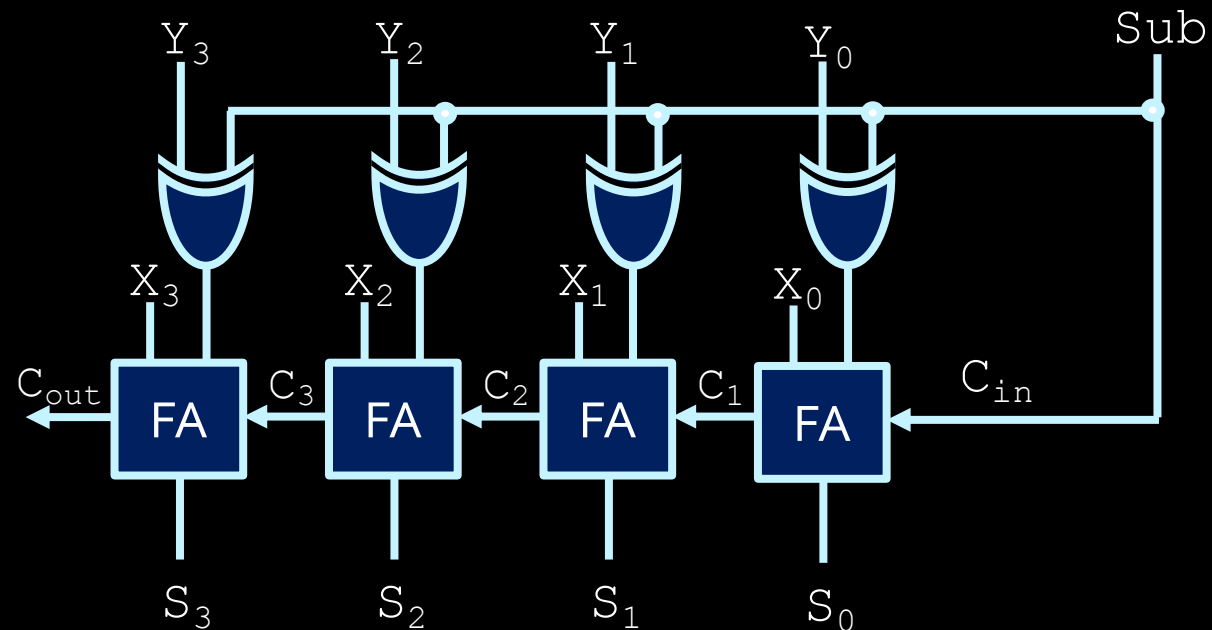
ALU outputs

- In addition to the input signals, there are output signals V, C, N & Z which indicate special conditions in the arithmetic result:
 - **V**: overflow condition
 - The result of the operation could not be stored in the n bits of G , meaning that the result is incorrect.
 - **C**: carry-out bit
 - **N**: Negative indicator
 - **Z**: Zero-condition indicator



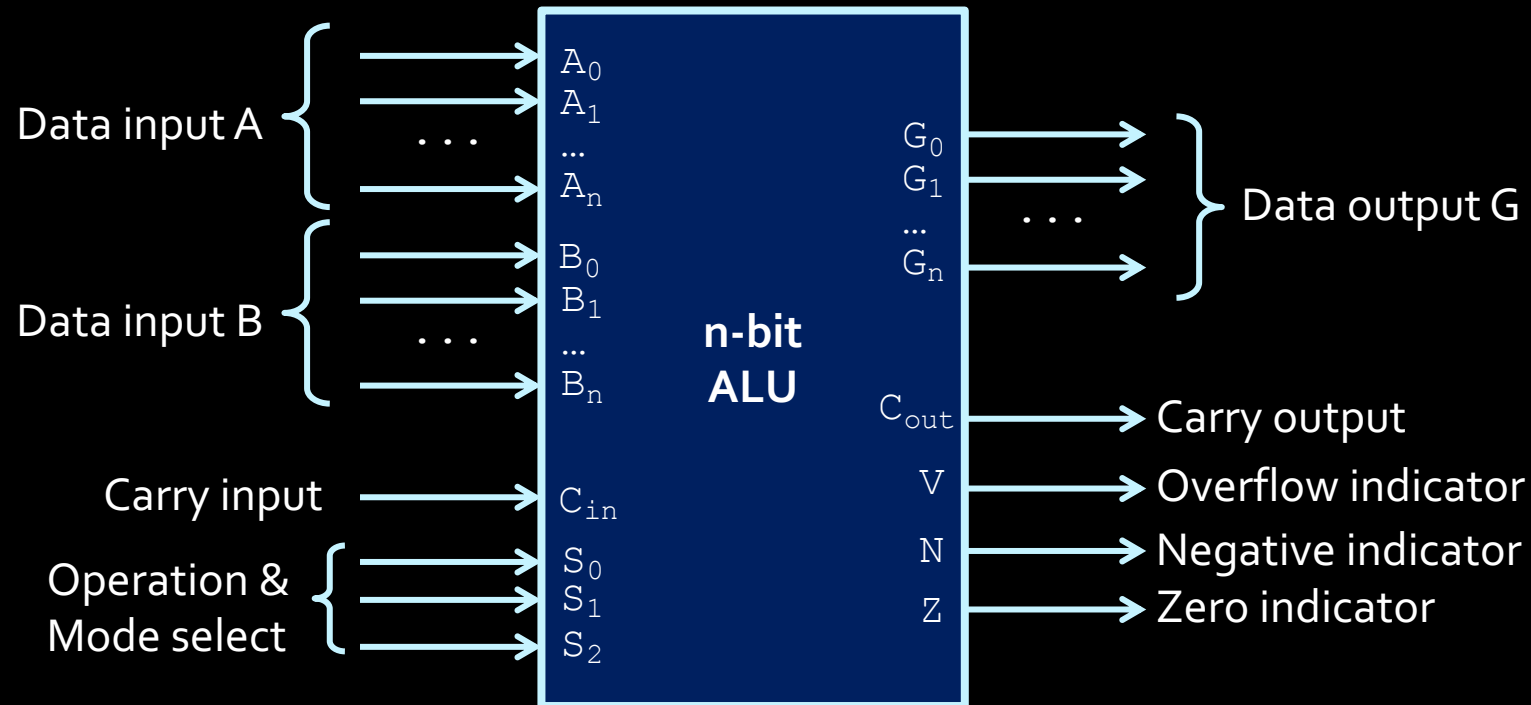
The “A” of ALU

- To understand how the ALU does all of these operations, let's start with the arithmetic side.
- Fundamentally, this side is made of an adder / subtractor unit, which we've seen already:

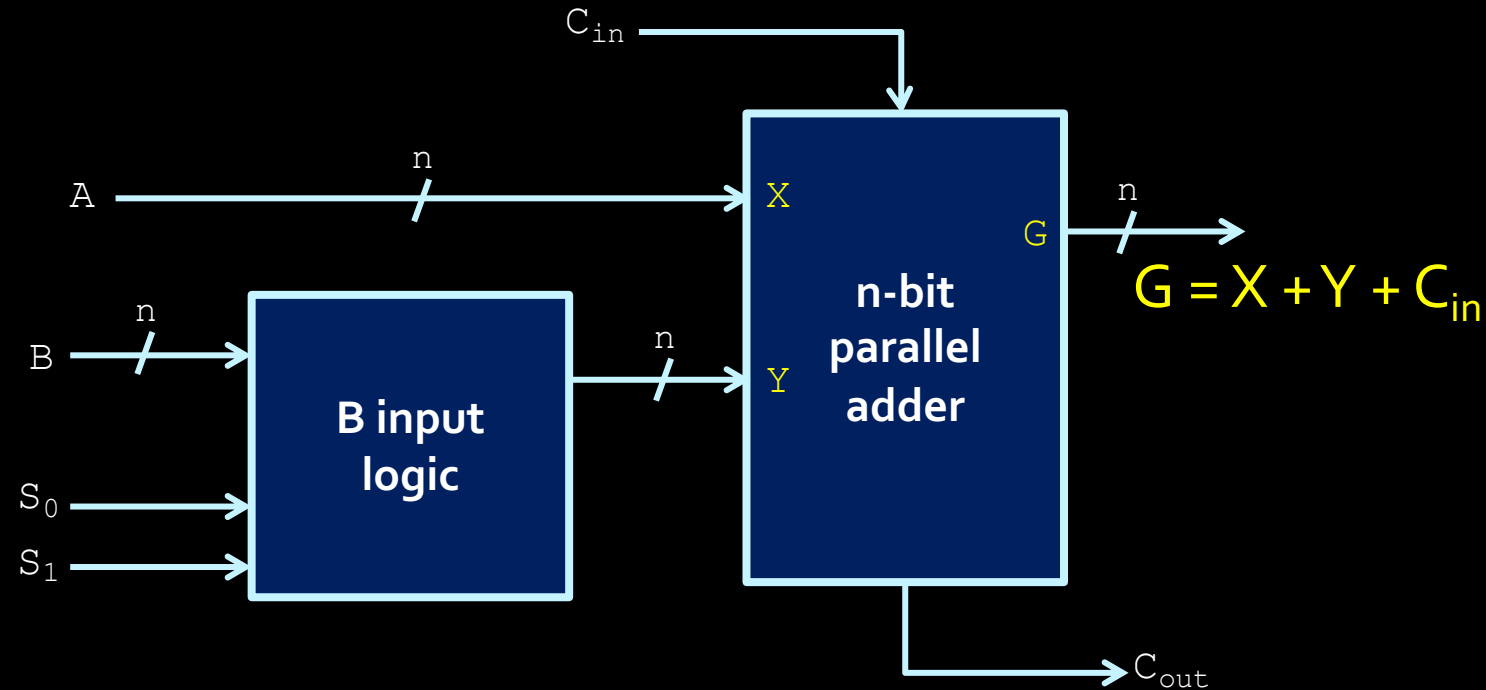


ALU block diagram

- In addition to data inputs and outputs, this circuit also has:
 - outputs indicating the different conditions,
 - inputs specifying the operation to perform (similar to `Sub`).

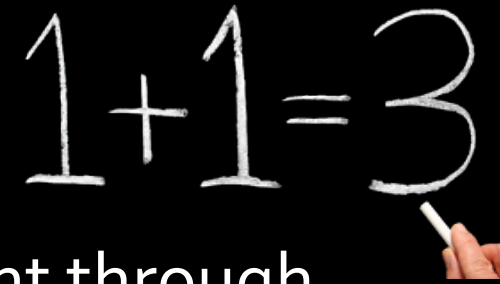


Arithmetic components



- In addition to addition and subtraction, many more operations can be performed by manipulating what is added to input B , as shown in the diagram above.

Arithmetic operations



A hand-drawn equation $1+1=3$ written in white on a black background. A hand is visible at the bottom right, holding a white marker and pointing to the number 3.

- If the input logic circuit on the left sends B straight through to the adder, result is $G = A+B$
 - What if B was replaced by all ones instead?
 - Result of addition operation: $G = A-1$
 - What if B was replaced by \bar{B} ?
 - Result of addition operation: $G = A-B-1$
 - And what if B was replaced by all zeroes?
 - Result is: $G = A$. (Not interesting, but useful!)
- Instead of a Sub signal, the operation you want is signaled using the select bits S_0 & S_1 .

Operation selection

Select bits		Y input	Result	Operation
S_1	S_0			
0	0	All 0s	$G = A$	Transfer
0	1	B	$G = A+B$	Addition
1	0	\bar{B}	$G = A+\bar{B}$	Subtraction - 1
1	1	All 1s	$G = A-1$	Decrement

- This is a good start! But something is missing...
- What about the carry bit?

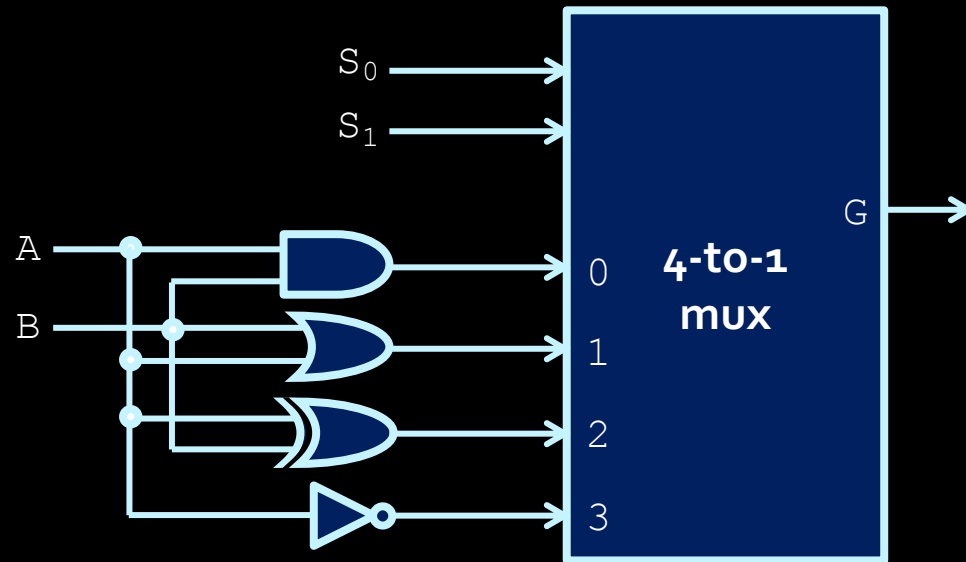
Full operation selection

Select		Input	Operation	
S_1	S_0	Y	$C_{in}=0$	$C_{in}=1$
0	0	All 0s	$G = A$ (transfer)	$G = A+1$ (increment)
0	1	B	$G = A+B$ (add)	$G = A+B+1$
1	0	\bar{B}	$G = A+\bar{B}$	$G = A+\bar{B}+1$ (subtract)
1	1	All 1s	$G = A-1$ (decrement)	$G = A$ (transfer)

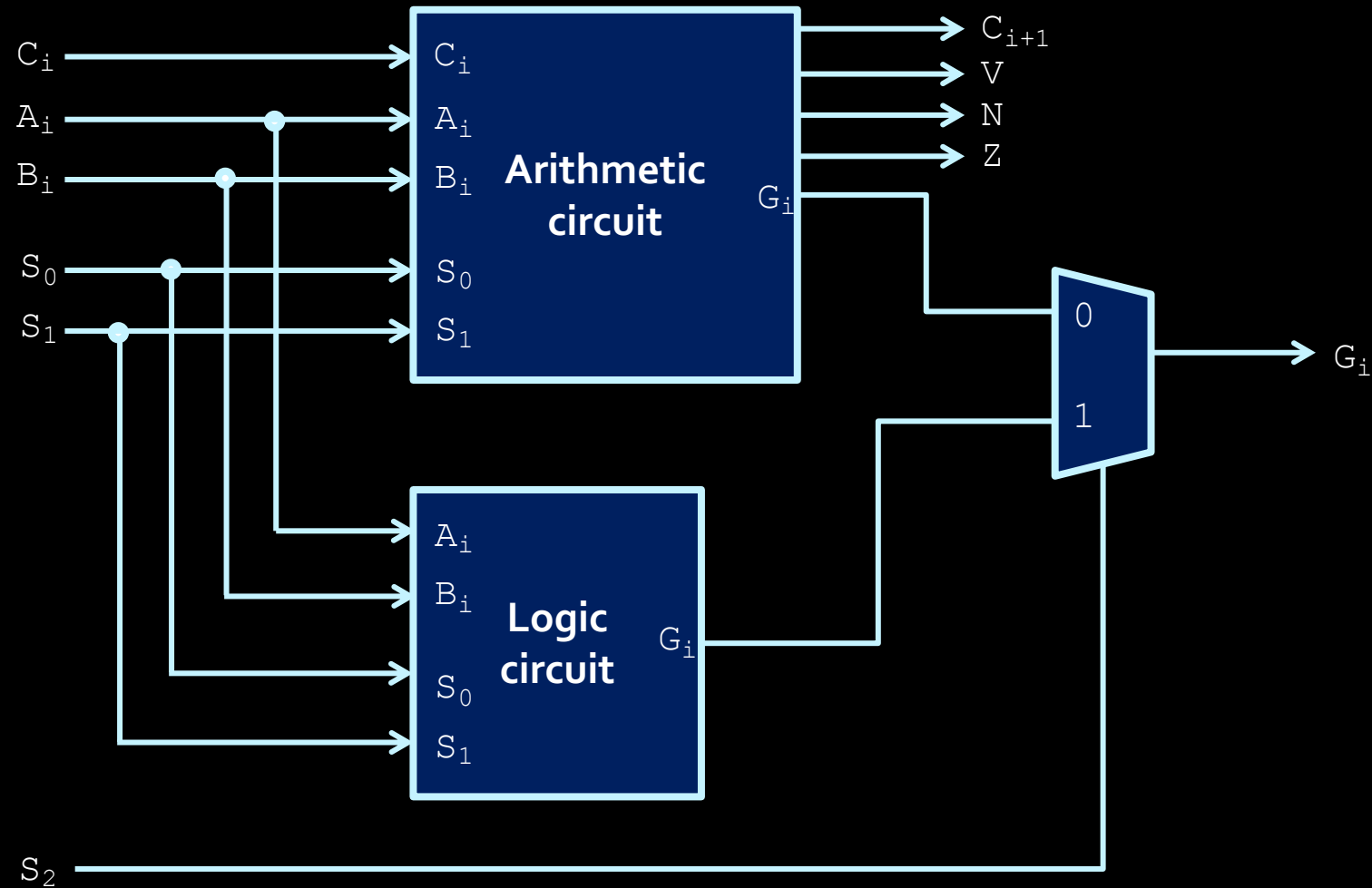
- Based on the values on the select bits and the carry bit, we can perform any number of basic arithmetic operations by manipulating what value is added to A .

The “L” of ALU

- We also want a circuit that can perform **logical operations**, in addition to arithmetic ones.
- How do we tell which operation to perform?
 - Another select bit!
- If $S_2 = 1$, then logic circuit block is activated.
- Multiplexer is used to determine which block (logical or arithmetic) goes to the output.



Single ALU Stage



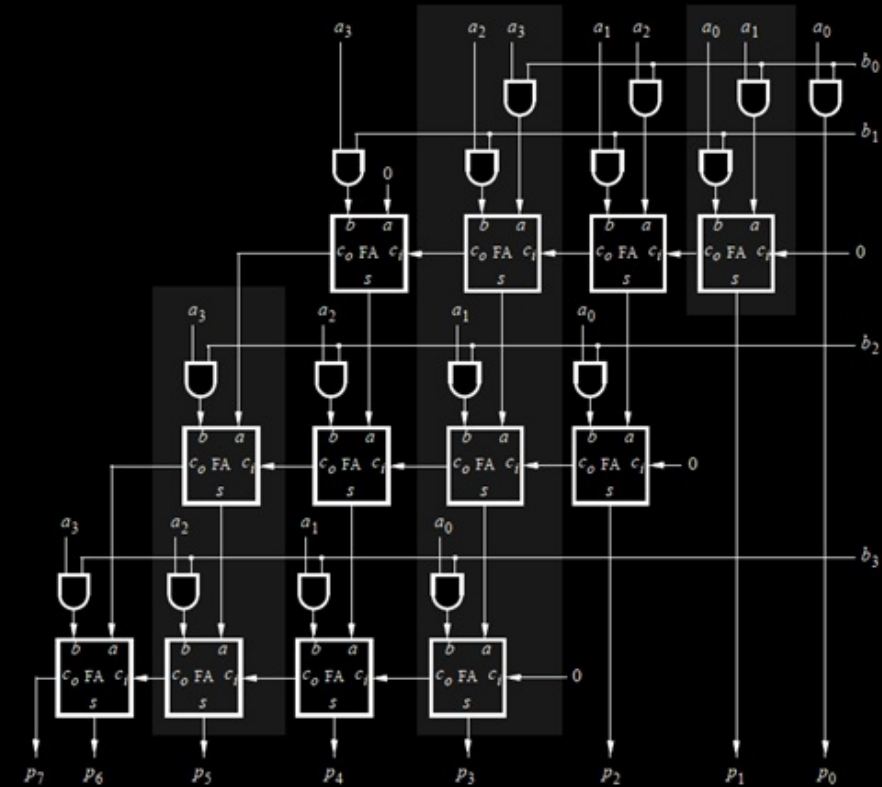
Multiplication

What about multiplication?

- Multiplication (and division) operations are always more complicated than other arithmetic (addition, subtraction) or logical (AND, OR) operations.
- Three major ways that multiplication can be implemented in circuitry:
 - Layered rows of adder units.
 - An adder/shifter circuit
 - Booth's Algorithm

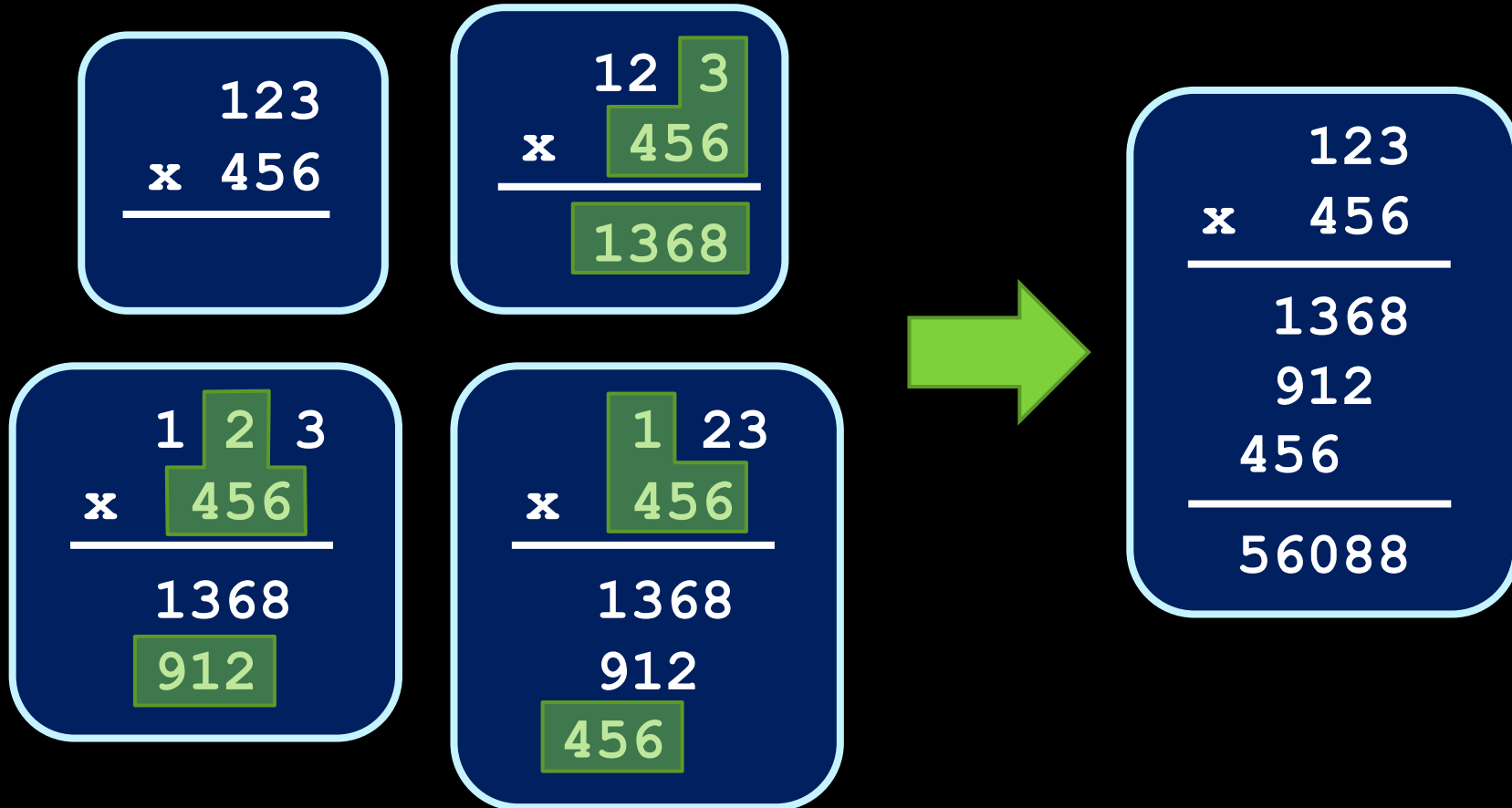
Multiplication

- Multiplier circuits can be constructed as an array of adder circuits.
- This can get a little expensive as the size of the operands grows.
- Is there an alternative to this circuit?



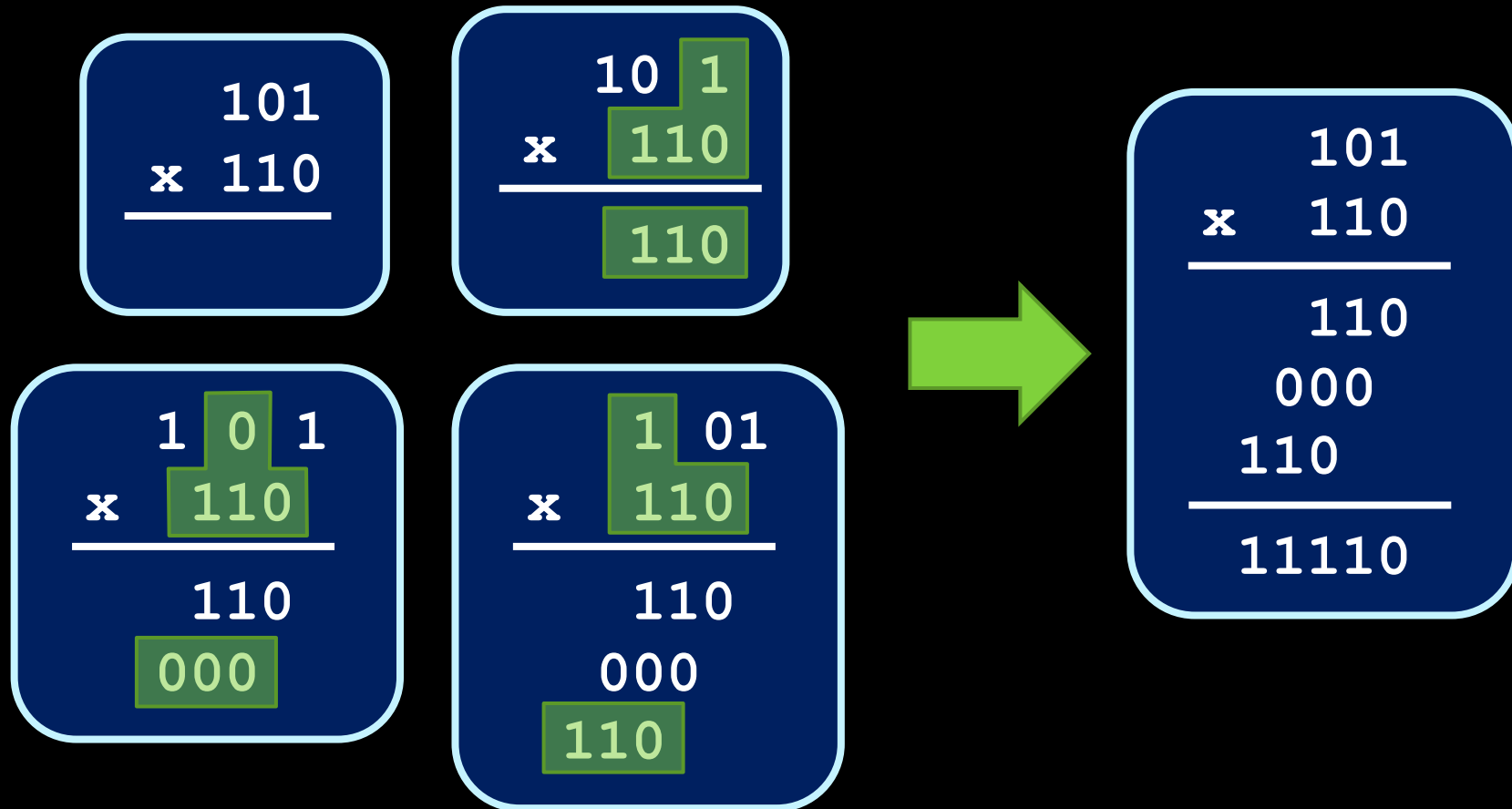
Multiplication

- Revisiting grade 3 math...



Multiplication

- And now, in binary...



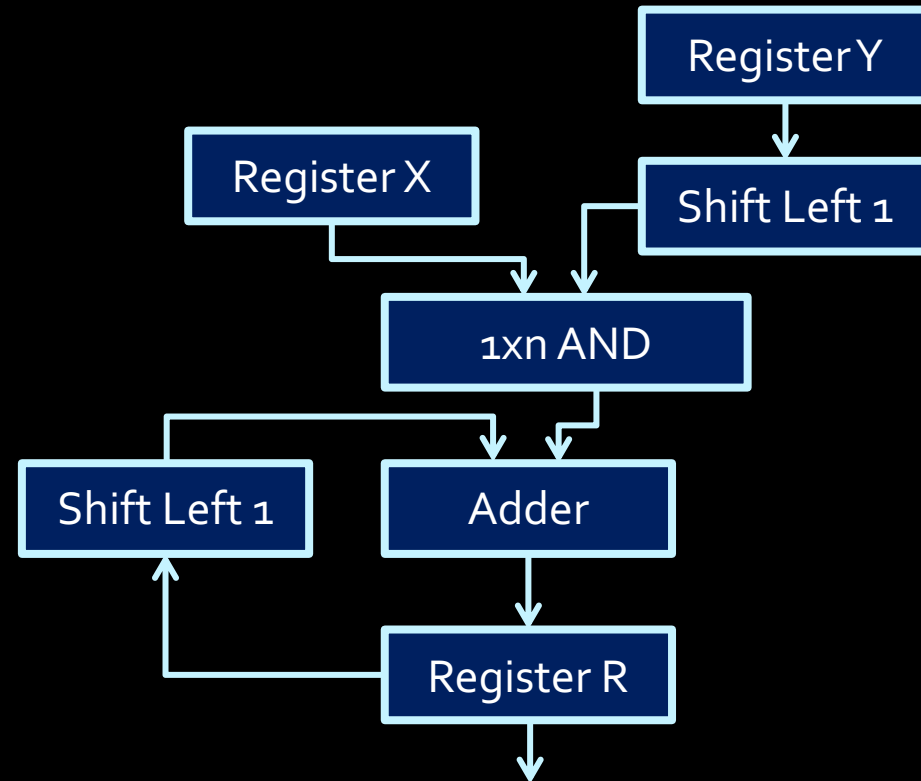
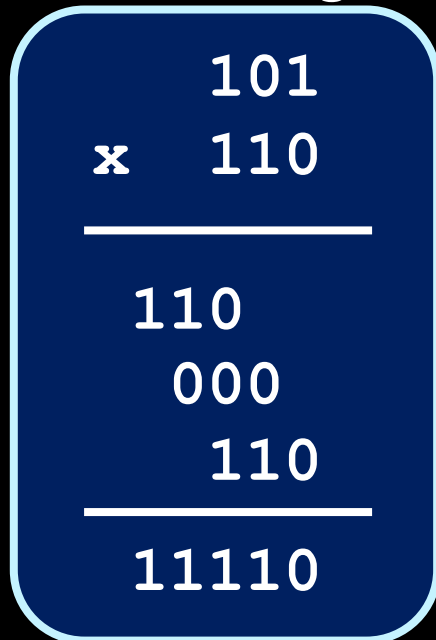
Observations

- Calculation flow
 - Multiply by 1 bit of multiplier
 - Add to sum and shift sum
 - Shift multiplier by 1 bit
 - Repeat the above
- What is “multiply by 1 bit of binary”?
 - 10101×1 ?
 - 10101×0 ?
 - It's an **AND**!

$$\begin{array}{r} 101 \\ \times 110 \\ \hline 000 \\ 110 \\ \hline 11110 \end{array}$$

Accumulator circuits

- What if you could perform each stage of the multiplication operation, one after the other?
 - This circuit would only need a single row of adders and a couple of shift registers.



Make it more efficient

Think about 258×9999

- Multiply by 9, add to sum, shift, multiply by 9, add to sum, shift, multiple by 9, add to sum, shift, multiply by 9, add to sum.
- $258 \times 9999 = 258 \times (10000 - 1) = 258 \times 10000 - 258$
- Just shift 258, becomes 2580000, then do $2580000 - 258$
- More efficient!

Efficient Multiplication: Booth's Algorithm

- Take advantage of circuits where **shifting is cheaper** than adding, or where space is at a premium.
 - when multiplying by certain values (e.g. 99), it can be easier to think of this operation as a difference between two products.
- Consider the shortcut method when multiplying a given decimal value X by 9999:
 - $X * 9999 = X * 10000 - X * 1$
- Now consider the equivalent problem in binary:
 - $X * 001111 = X * 010000 - X * 1$
- More details: https://en.wikipedia.org/wiki/Booth%27s_multiplication_algorithm

Reflections on multiplication

- Multiplication isn't as common an operation as addition or subtraction, but occurs enough that its implementation is handled in the hardware.
- Most common multiplication and division operations are powers of 2. For this, we do shifting instead of using the multiplier circuit.
 - e.g., in your code, do `x << 3`, instead of `x * 8`

